

A numerical approach to solving the equations of weakly ionised multifluid MHD

T.P. Downes

Dublin City University
&

Dublin Institute for Advanced Studies & National Centre for Plasma Science & Technology

27th Jan, 2014

Acknowledgements

The People

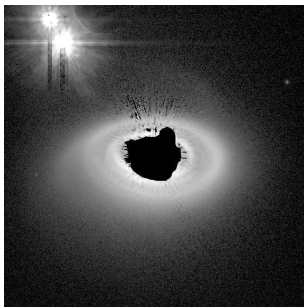
- Dr. Stephen O'Sullivan (DIT)
- Dr. Aoife Jones, Dr. Wayne O'Keeffe (former grad students)

The Organisations

- Irish Centre for High End Computing
- PRACE
- Science Foundation Ireland

Strong (Hall) diffusion

Protostellar disks



HD141569 Circumstellar Disk [NASA HST](#)

Strong (Hall) diffusion

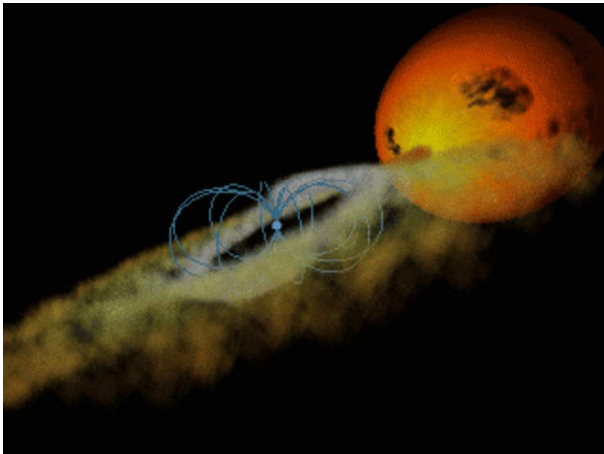
Dense molecular clouds



Horsehead Nebula [NASA HST](#)

Strong (Hall) diffusion

Dwarf nova disk



Derivation of the weakly ionised equations

We assume the equations of MHD, but with a non-zero “diffusive” term in the induction equation - i.e. the electric field in the fluid frame is non-zero.

The equation of motion for the charged species is then

$$\alpha_i \rho_i (\mathbf{E} + \mathbf{v}_i \times \mathbf{B}) = \nabla p_i + \rho_i \frac{D_i}{Dt} \mathbf{v}_i - \sum_{j \neq i}^N \mathbf{f}_{ij}$$

One can solve this system numerically, but better to simplify it if possible.

Weakly ionised approximation

- We presume that a neutral species dominates (by mass) the system and thus the overall velocity of the fluid(s) is roughly \mathbf{v}_1 .
- Neglect collisions between different charged species
- Neglect inertia (and pressure) of charged species

Weakly ionised approximation

The equation of motion of the charged species becomes

$$\alpha_i \rho_i (\mathbf{E} + \mathbf{v}_i \times \mathbf{B}) + \mathbf{f}_{i1} = 0$$

where

$$\mathbf{f}_{ij} = \mathbf{C}_{ij} + s_{ij} \mathbf{v}_j - s_{ji} \mathbf{v}_i$$

where

$$\mathbf{C}_{ij} = \rho_i \rho_j K_{ij} (\mathbf{v}_j - \mathbf{v}_i)$$

(we neglect terms with s , and K is related to the collision frequency)

Weakly ionised approximation

Now

$$\mathbf{J} = \sum_{i=1}^N \alpha_i \rho_i \mathbf{v}_i$$

We assume

$$\sum_{i=1}^N \alpha_i \rho_i = 0$$

and re-write our equations in the rest-frame of the neutral fluid:

$$\begin{aligned} \mathbf{E}' &= \mathbf{E} + \mathbf{v} \times \mathbf{B} \\ 0 &= \alpha_i \rho_i (\mathbf{E}' + \mathbf{v}'_i \times \mathbf{B}) - \frac{B}{\beta_i} (\alpha_i \rho_i \mathbf{v}'_i). \end{aligned}$$

where we introduce the Hall parameter, $\beta_i \equiv \frac{\alpha_i B}{\kappa_{1i} \rho_{i1}}$.

Weakly ionised approximation

Calculating \mathbf{J} from our equations of motion for the charged species we arrive (after a little algebra) at

$$\mathbf{J} = \sigma_{\parallel} \mathbf{E}'_{\parallel} + \sigma_{\perp} \mathbf{E}' + \sigma_{\text{H}} (\mathbf{E}' \times \mathbf{b})$$

where

$$\sigma_{\text{H}} = \frac{1}{B} \sum_{i=1}^N \frac{\alpha_i \rho_i}{1 + \beta_i^2},$$

$$\sigma_{\perp} = \frac{1}{B} \sum_{i=1}^N \frac{\alpha_i \rho_i \beta_i}{1 + \beta_i^2},$$

$$\sigma_{\parallel} = \frac{1}{B} \sum_{i=1}^N \alpha_i \rho_i \beta_i.$$

Weakly ionised approximation

We can invert this equation to get

$$\mathbf{E}' = r_0 \frac{(\mathbf{J} \cdot \mathbf{B})\mathbf{B}}{B^2} + r_1 \frac{\mathbf{B} \times \mathbf{J}}{B} + r_2 \frac{\mathbf{B} \times (\mathbf{J} \times \mathbf{B})}{B^2}.$$

This is our Generalised Ohm's Law for the weakly ionised case.

The weakly ionised equations

Our equations for our system are then:

$$\begin{aligned} \frac{\partial \rho_i}{\partial t} + \nabla \cdot (\rho_i \mathbf{v}_i) &= 0, \quad (1 \leq i \leq N), \\ \frac{\partial \rho_1 \mathbf{v}_1}{\partial t} + \nabla \cdot (\rho \mathbf{v}_1 \mathbf{v}_1 + a^2 \rho \mathbf{l}) &= \mathbf{J} \times \mathbf{B}, \\ \frac{\partial \mathbf{B}}{\partial t} + \nabla \cdot (\mathbf{v}_1 \mathbf{B} - \mathbf{B} \mathbf{v}_1) &= -\nabla \times \mathbf{E}', \\ \alpha_i \rho_i (\mathbf{E} + \mathbf{v}_i \times \mathbf{B}) + \rho_i \rho_1 K_{i1} (\mathbf{v}_1 - \mathbf{v}_i) &= 0, \quad 2 < i \leq N, \\ \nabla \cdot \mathbf{B} &= 0, \\ \nabla \times \mathbf{B} &= \mathbf{J}, \\ \sum_{i=2}^N \alpha_i \rho_i &= 0. \end{aligned}$$

Numerical technique

If we know \mathbf{B} we can advance these equations easily:

- Advance the neutral density and neutral momentum equations using an explicit upwind method (without source terms)
- Advance the charged density equations
- Apply the source term to the neutral momentum equation
- Advance magnetic field
- Algebraically solve for the charged gas velocities

This is done in an operator-split fashion

The induction equation

Consider the linearised induction equation

$$\frac{\partial \mathbf{B}}{\partial t} + \frac{\partial \mathbf{M}}{\partial \mathbf{x}} = r_O \mathbf{R}_O \frac{\partial^2 \mathbf{B}}{\partial \mathbf{x}^2} + r_H \mathbf{R}_H \frac{\partial^2 \mathbf{B}}{\partial \mathbf{x}^2} + r_A \mathbf{R}_A \frac{\partial^2 \mathbf{B}}{\partial \mathbf{x}^2}$$

where

$$\mathbf{B} = (B_y, B_z)$$

$$\mathbf{M} = (uB_y - vB_x, uB_z - wB_x)$$

The challenge

Discretise the induction equation, ignoring r_0 and assuming $\mathbf{B}_j^n = \mathbf{B}^n e^{i\omega j}$ to get

$$\mathbf{B}^{n+1} = \mathbf{A}\mathbf{B}^n$$

Stability requires the spectral radius of \mathbf{A} to be less than or equal to 1

Conventional methods

- Explicit methods:
 - Conventional schemes show poor stability for large Hall effect
($\Delta t \rightarrow 0$ as $\eta \equiv \frac{r_A}{r_H}$ becomes small)
 - Even for low η they require quite a low time-step ($\Delta t \propto (\Delta x)^{-2}$)
 - Simple to implement in multidimensional/parallel/adaptive codes
- Implicit methods:
 - Unconditionally stable
 - Difficult to implement in multidimensional/parallel/adaptive codes

We want it all: An explicit, stable method

Dealing with $\nabla \times \mathbf{E}'$

For diagonal terms (associated with r_2 and r_0 if large) use **Super Time-Stepping**:

- $\tau^{\text{STS}} = \sum_{i=1}^N d\tau_i$
- Require that $\left| \prod_{i=1}^N (1 - d\tau_i \hat{\lambda}) \right| < 1$
- $d\tau_i = \tau^{\text{STD}} \left[(-1 + \nu) \cos\left(\frac{2i-1}{N} \frac{\pi}{2}\right) + 1 + \nu \right]^{-1}$
- N and ν are user-defined
- $\tau^{\text{STS}} \rightarrow N^2 \tau^{\text{STD}}$ as $\nu \rightarrow 0$

Dealing with $\nabla \times \mathbf{E}'$

For the Hall term (r_1 term) use the “Hall Diffusion Scheme” which relies on the off-diagonal nature of the Hall operator.

An example: For a pure Hall operator (anti-symmetric operator) we might have the following discretisation:

$$(B_y)_i^{n+1} = (B_y)_i^n + \frac{\Delta t}{\Delta x^2} [(B_z)_{i+1}^n - 2(B_z)_i^n + (B_z)_{i-1}^n]$$

$$(B_z)_i^{n+1} = (B_z)_i^n + \frac{\Delta t}{\Delta x^2} [(B_y)_{i+1}^{n+1} - 2(B_y)_i^{n+1} + (B_y)_{i-1}^{n+1}]$$

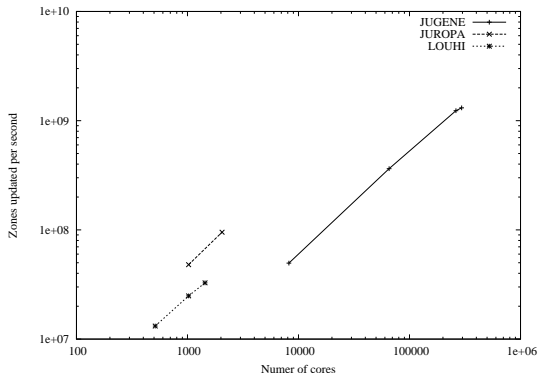
Explicit for B_y , implicit for B_z . Stability is good, though still have $\Delta t \propto \Delta x^2$.

How efficient is the resulting code?

For some standard tests we get the following timings (in seconds, for a serial code):

	Ambipolar dominated	Hall dominated	Sub-shock
Implicit	1.9	23.3	2.7
Explicit	1.9	14.8	1.9

Do the algorithms scale?



- Scaling for JuRoPA system is virtually perfect up to 2048 cores.
- Code scales (on BG/P systems) from 8192 cores up to 294912 cores with circa 70% efficiency.
- Performance on XT5 has since been improved ...

The importance of scaling

For some published turbulence simulations:

- On an 8-core workstation a 64^3 run takes about 12 hrs
- On the BG/Q with 4096 cores a 512^3 run takes about 1 day
- On an 8-core workstation a 512^3 run would take at least 6 years

Conclusions

- The weakly ionised approximation is very useful (approach can be extended to fully ionised)
- Explicit algorithms are both available and valuable
- Algorithm development should, if possible, allow for scaling
- There are still outstanding issues
 - What can be done if diffusion is very large?
 - Diffusion in rarefied regions sometimes dominates - can we ignore it?