Adaptive Mesh Refinement for multi-fluid simulations of the processes in the solar atmosphere

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Description of structured AMR



 $\label{eq:Figure: Graphical representation of AMR refinement levels (from $http://www.lsc.phy.cam.ac.uk/research/amr.shtml)$$

• Method for dynamically (de)refining the grid resolution.

- Allows simulations with large length and time-scales.
- Increased computational savings over a static grid approach.
- Increased storage savings over a static grid approach.
- Eeach mesh can be advanced independently using its own time step.
- Strict conservation by matching fluxes at grid boundaries.
- Easily parallelizable due to the logically rectangular patches.

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Some existing AMR packages

- Many non-generic AMR packages: Pluto, Enzo, Uintah, RAMSES, NIRVANA, A-MAZE, FLASH, AstroBEAR, ...
- Some generic structured AMR packages

Package name	Prog. language	Actively developed?
AMRClaw	F77,F90, Python	Last: January 2013 (Part of Clawpack)
ForestClaw	F77,F90, Python, C	In development, not yet available.
AMROC	C++	Last: November 2004
Boxlib	C, Fortran90	Last: November 2012
Chombo	C++	Last: March 2012
Paramesh	Fortran90	Last: March 2008. Support stopped.
SAMRAI	C++	Last: January 2013

- Freely available (to run and to visualize output)
- 2D and 3D.
- Multi-stepping
- Parallel (OpenMP and/or MPI)

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• Parallel (MPI) Adaptive Mesh Refinement (Fortran 90 and C)

- Multidimensional
- Structured Grid Blocks
- Portable
- User Tunable Load Balancing
- Support for Conservation Laws
- Distribution contains source code
- Builds upon user's existing codes
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- $\bullet~{\rm I/\,O}$ to Chombo HDF5 files

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Paramesh

$\underset{Basic \ usage}{Paramesh}$

Define the models dimensionality (amr_runtime_parameters)	7,	properties of each grid block, etc.
50	,	maxhlocks
2	!	ndim
0	!	12p5d
124	!	nxb
124	!	nyb
1	!	nzb
164	!	nvar
[]		
5	!	nguard
[]		
2	!	nboundaries
.true.	!	diagonals
.true.	!	amr_error_checking

Paramesh

Paramesh Basic usage (2)

Set up initial grid (sizes, locations, neighbours, boundaries)

```
lrefine_max = 10  ! finest refinement level allowed
lrefine_min = 6  ! coarsest refinement level allowed
```

```
if(mype.eq.0.) then
   bnd box(1,1,1) = 0. ! lower x bound of block 1
   bsize(1,1) = bnd_box(2,1,1) - bnd_box(1,1,1)
   coord(1,1) = .5*(bnd_box(2,1,1) - bnd_box(1,1,1))
   nodetype(1) = 1
                  ! identify block 1 as a leaf block
   lrefine(1) = 1  ! set refinement level of block 1
   neigh(1:2,1,1) = -21 ! left boundary condition
   lnblocks = 1
                          ! no. of blocks on this processor
endif
! x boundaries
boundary_box(1,2:3,1:2) = -1.e30 ! effectively this is -infinity
boundary_index(1)
                 = -21
```

Paramesh Basic usage (3)



Mesh details

- All grid blocks identical logical structure
- Logically cartesian
- When refined, a block spawns 4 child blocks (2D), same area but twice spatial resolution
- Neighbour leaf blocks differ at most by one refinement level

Paramesh

Paramesh Basic usage (4)

Use pointers in our code to link to Paramesh data structures

```
REAL(KIND=fp), DIMENSION(:,:), POINTER :: te, pe, rho
[...]
te => unk(1,:,:,1,block)
pe => unk(2,:,:,1,block)
rho => unk(3,:,:,1,block)
```



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AMR for multi-fluid simulations

Paramesh

```
Paramesh
Basic usage (5)
```

Load initial solution and evolve

```
time = 0.
call initial_soln(mype)
```

```
do loop=1,ntsteps
    call amr_guardcell(mype,iopt,nlayers)
```

! advance and amr_test_refinement: user defined call advance(mype,dt,time,nprocs,loop) call amr_test_refinement(mype,lrefine_min,lrefine_max)

```
call amr_refine_derefine
  call amr_prolong(mype,iopt,nlayers)
enddo
```

```
call amr_close()
```

Multi-grid example

Whole domain	Detail		
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Adaptive mesh example: Rayleigh-Taylor instability

Whole domain	Detail

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Adaptive mesh example: RTI Mesh refinement dynamics



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AMR for multi-fluid simulations

Adaptive mesh example: RTI Paramesh computation overhead



Adaptive mesh example: RTI Grid blocks distribution



Adaptive mesh example: RTI Parallel performance



Notes

- Poor scalability in single node due to cache misses (also present in serial and MPI versions)
- Poor scalability across nodes due to high communication requirements
- Cache misses have even bigger impact than network communication
- Parallel performance similar to that of own MPI version

On-going work

Variable Timestep t -----..... Block A Block B Block C Block D Figure: Variable timestep flow-chart (from http://www.physics.drexel.edu/~olson/parameshdoc/Users manual/amr variable dt.html)

Notes

- Need loads of extra storage
- Flow-chart can get quite complex
- Now not all blocks do the same work: block balance?

- Adding Paramesh not too difficult (specially if starting from scratch)
- CPU overhead quite large, so we need to be carefull when defining the refinement function if we are to get performance gains
- Memory overhead not too large for constant timestep, but quite large for variable timestep
- Minor drawback: blocks are not dinamycally allocated, but rather fixed in amr_runtime_parameters
- Paramesh has other features that we didn't discuss: divergenceless prolongation, conservation laws, checkpointing, ...

- Adaptive mesh refinement for hyperbolic partial differential equations M. Berger, J. Oliger J. Comp. Phy. 1984 http://www.sciencedirect.com/science/article/pii/0021999184900731
- Local adaptive mesh refinement for shock hydrodynamics M. Berger, P. Colella J. Comp. Phy. 1989 http://www.sciencedirect.com/science/article/pii/0021999189900351
- Paramesh V4.1 webpage: http://www.physics.drexel.edu/õlson/paramesh-doc/Users manual/amr.html