

Laboratoire d'Études Spatiales et d'Instrumentation en Astrophysique

Excitation mechanisms (Sun, subgiants, & red giants)

K. Belkacem







PARIS DIDEROT



• P-modes in the Sun and main-sequence stars

- G-modes in the Sun
- Mixed-modes in sub giants and red giants



• P-modes in the Sun and main-sequence stars

- G-modes in the Sun
- Mixed-modes in sub giants and red giants



Energetics of solar-like oscillations

• Solar-like oscillations are damped and forced oscillations

$$\frac{\mathrm{d}}{\mathrm{d}t}A^2 \propto \mathcal{P} - \eta A^2$$

Stationarity
$$\longrightarrow A^2 \propto \frac{\mathcal{P}}{\eta}$$

mode amplitudes = balance between damping and driving



Energetics of solar-like oscillations

• Solar-like oscillations are damped and forced oscillations

$$\frac{\mathrm{d}}{\mathrm{d}t}A^2 \propto \mathcal{P} - \eta A^2$$



mode amplitudes = balance between damping and driving

Driving (P): "Stochastic excitation" by turbulent eddies



- eddies drive « randomly » the normal modes
- modes are excited in the upper-most layers of stars where turbulence is important
- typically a region of 3 Mm depth for the Sun



• For the Sun, the modeling of mode driving was a long process







- The main physics for p-mode driving is grasped
- The dominant forcing is due to the Reynolds stresses



- The main physics for p-mode driving is grasped
- The dominant forcing is due to the Reynolds stresses
- Still some problems:

- at high frequencies, mainly related to the separation of scales assumption

- treatment of non-isotropic turbulence
- need to improve the observational constraints !





Energetics of solar-like oscillations

• Solar-like oscillations are damped and forced oscillations

$$\frac{\mathrm{d}}{\mathrm{d}t}A^2 \propto \mathcal{P} - \eta A^2$$

LESIA

oservatorre



- typically a region of 3 Mm depth for the Sun

Computation of mode damping is a difficult task:



It remains an open problem:

I) Reynolds stress approach for modeling convection (Xiong et al. 1977, 1989, 2000, 2010, ...)

unstable intermediate degree pmodes are found
most of the problems arise from

 A^2

the closures



It remains an open problem:

I) Reynolds stress approach for modeling convection (Xiong et al. 1977, 1989, 2000, 2010, ...)

II) Non-local mixing-length formalisms with timedependent treatment of convection

• Balmforth (1992); Houdek et al. (1999); Chaplin et al. (2005) based on Gough's theory of convection

• Grigahcène et al. (2005); Dupret et al. (2006) based on Unno's theory of convection

- unstable intermediate degree pmodes are found
- most of the problems arise from the closures

- all modes are found stable
 stabilisation: perturbation of turbulent pressure
- all modes are found stable
- stabilisation: perturbation of convective flux





• Thus, the firsts attempts to confront theoretical computations and observations ... were not very convincing



Disagreement on the dominant contribution to the dampings

• Thus, the firsts attempts to confront theoretical computations and observations ... were not very convincing



« With four parameters I can fit an elephant and with five I can make him wiggle his trunk. » John von Neumann

• To get some clues on the free parameters, several approaches are possible

 \checkmark free parameters are constrained: non-local parameters with 3D models & closure parameter with the observed scaling relations (Belkacem et al. 2012)



• To get some clues on the free parameters, several approaches are possible

 \checkmark free parameters are constrained: 3D structure (turbulent pressure, etc...) & turbulent anisotropy (Houdek et al. 2017)



The problem is that some parameters (nonlocal parameters) are not fitted to the 3D models

When all free parameters are constrained with the 3D simulation = no solution ! (Sonoi, private comm)



Since they have unrealistic values, they « engulf » all the problems of the theory



Quite obvious because you try to reproduce a very complex physics with a very simple model...



• Is the main physical «picture» grasped?



Not obvious, certainly the main actors are identified but their relative contributions remain to be properly determined

Need to go beyond 1D models (even if constrained using 3D models)



New approaches are needed

• For g modes and especially for low-order ones, damping is thus very uncertain because extrapolation from p-modes would be dangerous



• P-modes in the Sun and main-sequence stars

- G-modes in the Sun
- Mixed-modes in sub giants and red giants



G modes : why it is so difficult to detect them ?



Credit: J. Christensen-Dalsgaard

- G modes are evanescent in the convective region
- Driving is related to mode compressibility $\frac{\delta \rho}{\rho} \propto \frac{\partial \xi_r}{\partial r}$

G mode amplitudes: what are the expected excitation mechanisms ?

There are mainly two candidates

✓ Excitation by penetrative convection at the base of the convective zone

✓ Excitation, as for p modes, by turbulent convection

G mode amplitudes: what are the expected excitation mechanisms ?

There are mainly two candidates

✓ Excitation by penetrative convection at the base of the convective zone

✓ Excitation, as for p modes, by turbulent convection

Schematic picture of penetrative convection



Waves (progressive and/or stationnary)

Some numbers



The Reynolds number:

defined as the ratio between inertia forces and viscous forces



At the top of the CZ: $R_e \sim 10^{13}$ At the bottom of the CZ: $R_e \sim 10^{10}$

Plumes are highly turbulent structures

Waves (progressive and/or stationary)

Some numbers



The Péclet number: defined as the ratio between inertia and radiative losses



Thermal diffusivity

 $P_e \le 1$: overshoot regime, i.e. plumes penetrate into RZ, thermally adjust to the environment and go on under the action of their inertia

Regime obtained in most of numerical simulations

 $P_e >> 1$: penetration regime, i.e. plumes penetrate into RZ, remain quasi-adiabatic. Hence, plumes are strongly slowed down

Regime in the Sun, P_{e} ~ 10⁷ at the bottom of the CZ

Waves (progressive and/or stationary)

Historical overview



Work by Andersen (1992, 1994, 1996)

- 2D cartesian numerical simulations
- Investigate the amplitude ratios between the two stable regions

10.

Horizontal velocity (mm⁻¹)

2

50

100

150

Frequency (µHz)

200

250

300

0.01

stable region convective region ad-hoc forcing at the base of the CZ stable region Assuming 1 mode excited Assuming 1000 modes excited

$$\ell = 6 \begin{bmatrix} V \approx 0.01 - 5 \text{ mm.s}^{-1} \end{bmatrix}$$

Dintrans et al. (2005)



Up to 40% of the kinetic energy can be supplied to the modes Life-time of modes ~ 2 periods

• <u>Rogers et al. (2006)</u>

2D numerical simulations with a realistic stratification

IGW were found in the radiative region but it was unclear if g-modes were excited



• <u>Rogers et al. (2006)</u>

2D numerical simulations with a realistic stratification

IGW were found in the radiative region but it was unclear if g-modes were excited

• <u>Alvan et al. (2015)</u>

3D numerical simulations using the ASH code

G-modes seem to be efficiently excited but it is unclear if it is due to the turbulent convection or penetrative convection



Can 2D and 3D simulations can help to settle the issue?

Can 2D and 3D simulations can help to settle the issue?

• The effective Peclet numbers are far from being realistic (i.e. in 3D near unity rather than 10⁷)

Can 2D and 3D simulations can help to settle the issue?

- The effective Peclet numbers are far from being realistic (i.e. in 3D near unity rather than 10⁷)
- To be thermally relaxed (and not only dynamically): no choice than to use some tricks

e.g. Rogers & Glatzmaier (2005) radiative diffusivity is tuned to allow for computable time-scales



The obtained convective flux is 10⁵ higher than the solar one!!

Can 2D and 3D simulations can help to settle the issue?

- The effective Peclet numbers are far from being realistic (i.e. in 3D near unity rather than 10⁷)
- To be thermally relaxed (and not only dynamically): no choice than to use some tricks

e.g. Rogers & Glatzmaier (2005) radiative diffusivity is tuned to allow for computable time-scales



The obtained convective flux is 10⁵ higher than the solar one!!

• Last but not least: inner boundary conditions

Due to the artificially low radiative diffusivity, internal gravity waves are hardly dissipated



Part of the energy is then \ll catched \gg into g modes

So, simulations are useful but are still models and do not (yet?) provide an answer concerning excitation of g modes

G mode amplitudes: what are the expected excitation mechanisms ?

There are mainly two candidates

✓ Excitation by penetrative convection at the base of the convective zone

✓ Excitation, as for p modes, by turbulent convection

As for p modes: stochastic excitation by turbulent convection

- Turbulent eddies excite randomly the modes
- for g modes excitation takes place in the deep convective layers



Historical overview



Equipartition "principle"

Used by Gough (1985) (see also Berthomieu & Provost 1990)

$$V^2 \propto \frac{P}{\eta} = E_{\rm osc}$$

equipartition = equipartition of kinetic energy between an acoustic mode and the resonant eddy

This assumption permits to avoid the computation of P and η

Pb: demonstrated by Goldreich & Keeley (1977b) for p modes under the assumption that damping is dominated by turbulent viscosity

• No evidence it works for g modes, No evidence the damping is dominated by turbulent viscosity (very unlikely for p modes !!)



First full calculation (i.e. excitation + damping): Kumar et al. (1996)

Mode excitation

Adapted from the modeling of *p* modes (Goldreich et al., 1994)



Mode damping

Adaptation of the Goldreich & Kumar (1991) formalism

✓ Radiative damping

✓Turbulent viscosity: analogy with molecular viscosity, small-scale eddies (compared to the mode wave-length) generate an effective viscosity for modes

First full calculation (i.e. excitation + damping)





Belkacem et al. (2009)

- For the excitation
- determination of turbulent properties using the ASH code (in particular Lorentzian eddy-time correlation function)

- Full non-radial computation is performed but only for asymptotic g-modes
- ➡ to get rid of the uncertainties linked to the treatment of convection, turbulent pressure etc...
- ➡ to avoid any extrapolation from the observed p modes
- Damping dominated by radiative losses



Belkacem et al. (2009)

- Taking into account visibility factors as well as limb darkening
- ➡l > 3 highly damped, detection unlikely (η∝l²)
- ➡Still some uncertainties, mainly related to the turbulent velocities at the base of the convective zone





Some concluding remarks about g-mode excitation models...

« Essentially, all models are wrong, but some are useful. »

George E. P. Box, *Empirical Model-Building and Response Surfaces*, 1987



• P-modes in the Sun and main-sequence stars

- G-modes in the Sun
- Mixed-modes in sub giants and red giants



From scarcity to abundance: evolved stars



- hundreds of oscillating MS stars and thousands of RG stars
- highly accurate measurements of individual mode properties



From scarcity to abundance: evolved stars





From scarcity to abundance: evolved stars



• The oscillations of red-giants differ significantly from main-sequence stars



the power spectrum of sub-giants and red-giants is largely modified by *mixed modes*



• The oscillations of red-giants differ significantly from main-sequence stars



the power spectrum of sub-giants and red-giants is largely modified by *mixed modes*



 \checkmark upper cavity in which acoustic modes can exist

the restoring force is dominated by the pressure gradient

 \checkmark inner cavity in which gravity modes can exist the dominant restoring force is the buoyancy

✓ intermediate region, in which modes are evanescent, couples the cavities



• The oscillations of red-giants differ significantly from main-sequence stars



the power spectrum of sub-giants and red-giants is largely modified by *mixed modes*



• Mixed modes have amplitude in the enveloppe and in the core

 \checkmark upper cavity in which acoustic modes can exist

the restoring force is dominated by the pressure gradient

 \checkmark inner cavity in which gravity modes can exist the dominant restoring force is the buoyancy

✓ intermediate region, in which modes are evanescent, couples the cavities



can be used to probe the innermost layers



• How mixed modes modify the power spectrum?



The second ingredient is the radiative damping in the core

1

As the star evolves, the radiative damping of g-dominated modes increases

$$\eta_{\rm rad} \propto rac{LR}{GM^2} \left(rac{R}{r_{
m core}}
ight)^2$$









for subgiants and early red giants mixed modes experience the same driving and damping as for pmodes. Only mode inertias are modified (model A)







for subgiants and early red giants mixed modes experience the same driving and damping as for pmodes. Only mode inertias are modified (model A)

for more evolved red giants, radiative damping begins to reduce mixed mode amplitudes (model B)







for subgiants and early red giants mixed modes experience the same driving and damping as for pmodes. Only mode inertias are modified (model A)

for more evolved red giants, radiative damping begins to reduce mixed mode amplitudes (model B)

for highly evolved stars radiative damping prevent mixed modes from being observed (model C)





for subgiants and early red giants mixed modes experience the same driving and damping as for pmodes. Only mode inertias are modified (model A)

for more evolved red giants, radiative damping begins to reduce mixed mode amplitudes (model B)

for highly evolved stars radiative damping prevent mixed modes from being observed (model C)



similar behaviors for the same number of mixed modes by large separation

 for red-giants, there are not (at least yet) precise measurements of linewidth of mixed modes

<u>Application:</u> inferring mode inertias (from Benomar et al. 2014)

• Mode height reads $H = \frac{\mathcal{P}}{2\eta^2 \mathcal{M}}$

• Finally,

- Consider two modes at roughly the same frequency, namely a p-dominated and g-dominated
- Since the two modes have the same shape at the surface

new constraint for theoretical models

$$\mathcal{P}_{i} \propto \frac{1}{\mathcal{M}_{i}} \int dW \xrightarrow{\text{modes experience the same work at the surface}} \mathcal{P}_{p}\mathcal{M}_{p} \approx \mathcal{P}_{g}\mathcal{M}_{g}$$
nally,
$$\underbrace{\mathcal{M}_{g}}_{\mathcal{M}_{p}} \neq \sqrt{\frac{H_{p}}{H_{g}}} \frac{\eta_{p}}{\eta_{g}}$$
inferred quantities
mode inertia ratio is derived from the observations:

 $\frac{H_p}{H_q} = \left(\frac{\mathcal{P}_p}{\mathcal{P}_q}\right) \left(\frac{\mathcal{M}_g}{\mathcal{M}_p}\right) \left(\frac{\eta_g}{\eta_p}\right)$

250

300

350

400

Frequency (μ Hz)

450

500