

### PHOTO-Z CHALLENGES FOR WL SPACE MISSIONS

JEAN-PAUL KNEIB EPFL

Jouvel et al 2009, 2011

### MOTIVATION

**Imaging survey:** shapes of  $\sim 10^9 - 10^{10}$  galaxies (WL)

$$<\gamma^2>\sim 0.01^2 \sigma_8^2 \Omega^{1.6} z_s^{1.4} \theta^{-(n+2)/2}$$

#### Redshift survey: bring 3rd dimension

- Photo-z: (useful for WL, clusters => DE, MG)
  - (-) less accurate => need calibration
  - (+) larger number of galaxies
- **Spectro-z**: (SN, calibration, BAO, clusters =>Cosmography)
  - (+) More accurate => provide calibration to photo-z
  - (-) Smaller number of galaxies

### PHOTO-Z HOW-TO?

Start with a telescope

Define/Use a filter set with N filters

Observe a fraction of sky in N multi-bands – (possibly adjust the exposure time for each filter)

Identify objects – observed in M bands (3<M<N)</p>

Compute photometric redshift (template fit, neural network, CNN, ...)

Compare to spectroscopic redshift => improve photo-z

### **PHOTO-Z SURVEY OPTIMISATION**

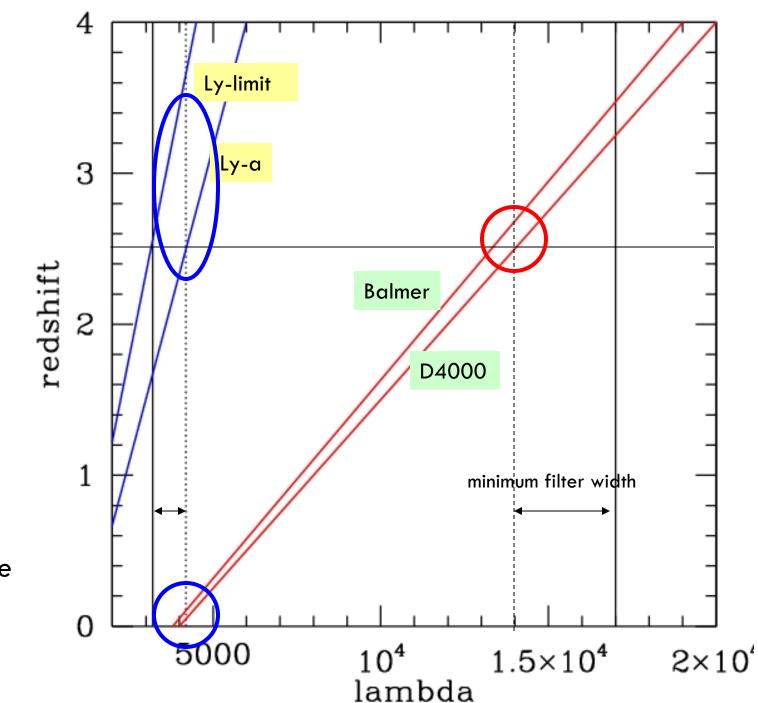
**Aim:** optimize (imaging, spectro survey) for the best DE experiment. For Photo-z:

- minimize catastrophic redshift fraction
- Minimize photo-z dispersion
- Minimize photo-z bias

**Photo-z:** sensitive on color gradients e.g: « breaks »: Lyman, D4000

#### Important parameters:

- Wavelength coverage: cover at least one "break" at any redshift (catastrophic z)
- Number of filters (photo-z precision)
- Filter resolution (Image depth) (photo-z precision)
- Size of spectroscopic redshift survey (photo-z bias)



Ideally have the 2 breaks in the wavelength range

### **QUICK ESTIMATE OF PHOTO-Z ACCURACY**

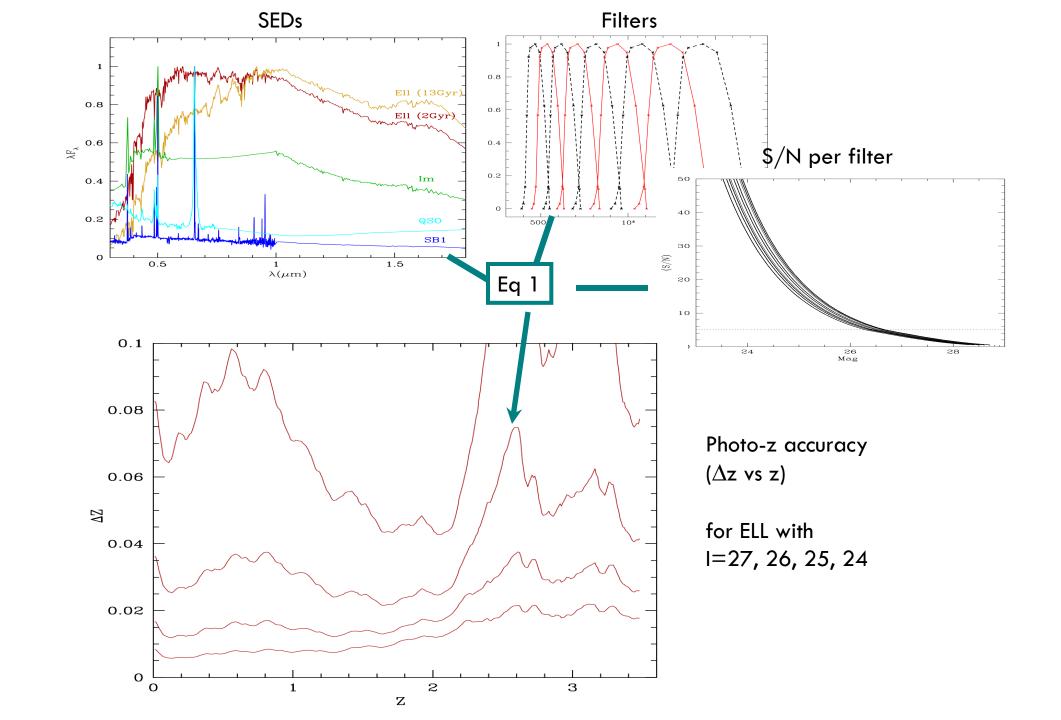
Photometric Redshift accuracy relies on the combination of **color gradients**: It can be expressed by considering all the color gradients : (Capak et al)

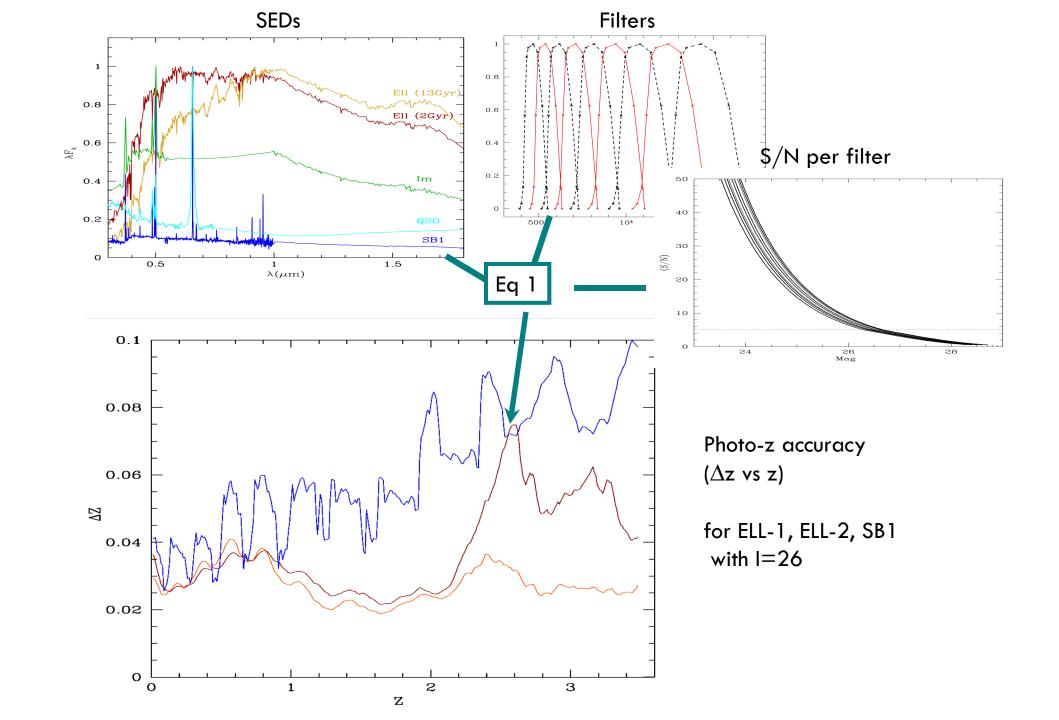
$$\frac{1}{\Delta z^2} = \sum_{i=0}^{i=n} \sum_{j=i+1}^{j=n} (\frac{\Delta C_{i,j}}{\Delta z} \frac{1}{dC_{i,j}})^2 \qquad \text{(Equation 1)}$$

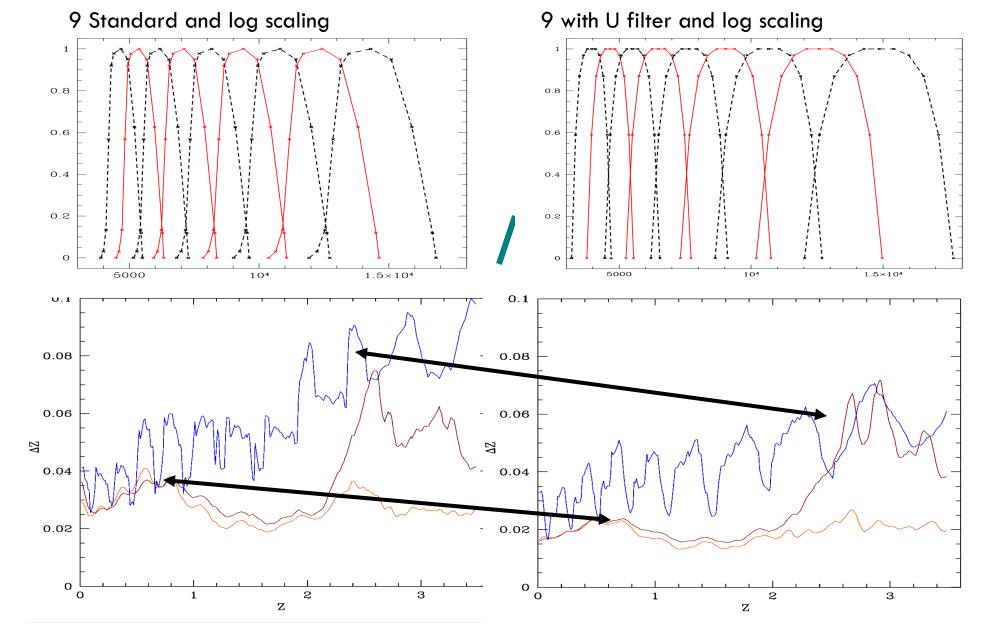
$$\frac{\Delta C_{i,j}}{\Delta z} \text{ is the color gradient } C_{i,j} \text{ with } z: \text{ depends on SED}$$

$$\frac{dC_{i,j}}{dC_{i,j}} \text{ is the photometric error : depends on survey performance}$$

Allow to estimate the performance for a given survey Depending on the filter set and the SED templates.

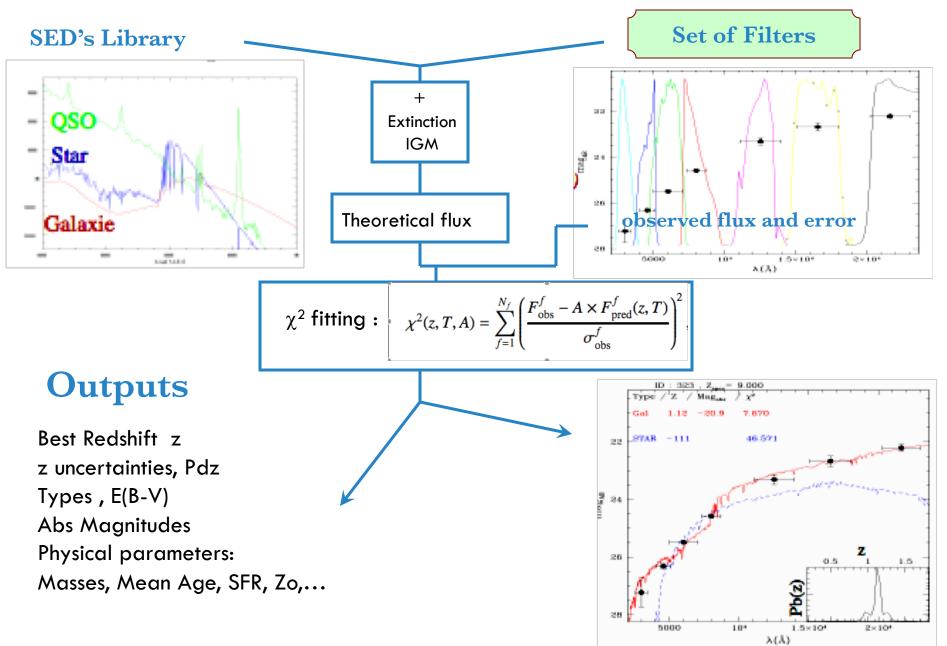






Gain to add a U band filters which depends on (z, SED)

#### **PHOTO-Z BY FITTING TEMPLATE SED (LE PHARE)**

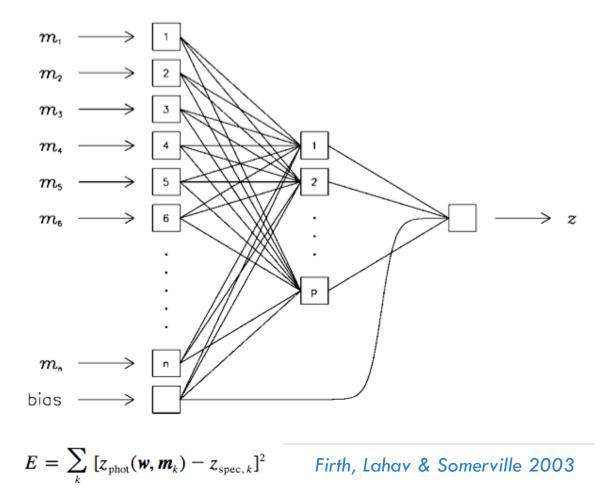


#### NEURAL NET/(NOW CNN) TRAINED BY DATA

Pseudo-PDF from

- 'Gaussian input ensemble'
- 'Committee' of networks
- no prior knowledge of SED, all the information is in the training sample
  available neural-net

output only photo-z



# **PHOTO-Z METHOD COMPARISON**

#### Fitting with SED model:

Predictive method (lower luminosity, higher-z ...)

Calibration of SED template with spectro-z

More difficult to evaluate size of spectro-z sample (how extended are the galaxy population?)

#### **Neural Net model:**

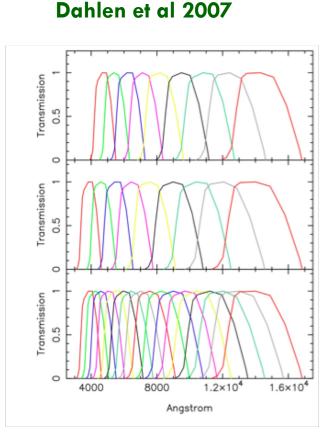
Training with spectro-z galaxy sample

Best results if working sample « similar » to training set sample

Powerful to use to estimate size of spectro-z calibration sample

Possibly the ultimate method is an hybrid one

### **INVESTIGATING THE SNAP PHOTO-Z**



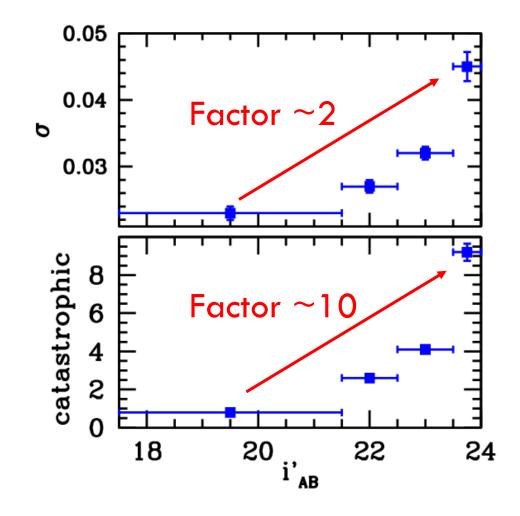
#### Method:

We create a mock galaxy catalog and use the *template fitting method* to calculate photo-z and compare with input 'spec-z'.

#### **Conclusion:**

- 9-filter set extended to U-band is preferred
- Phot-z accuracy highly dependent on limiting magnitude (S/N)
- Outlier fraction can be reduced using D95 while "maximizing"number of objects

## **ACCURACY PER MAGNITUDE BINS**



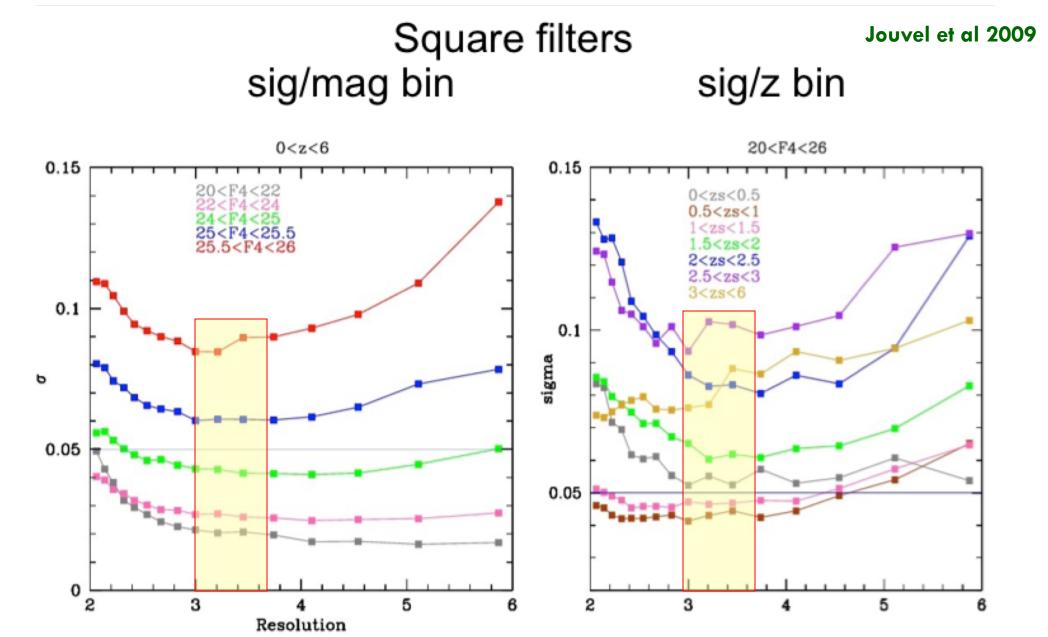
Apparent magnitude (S/N) is a key parameter in photo-z accuracy

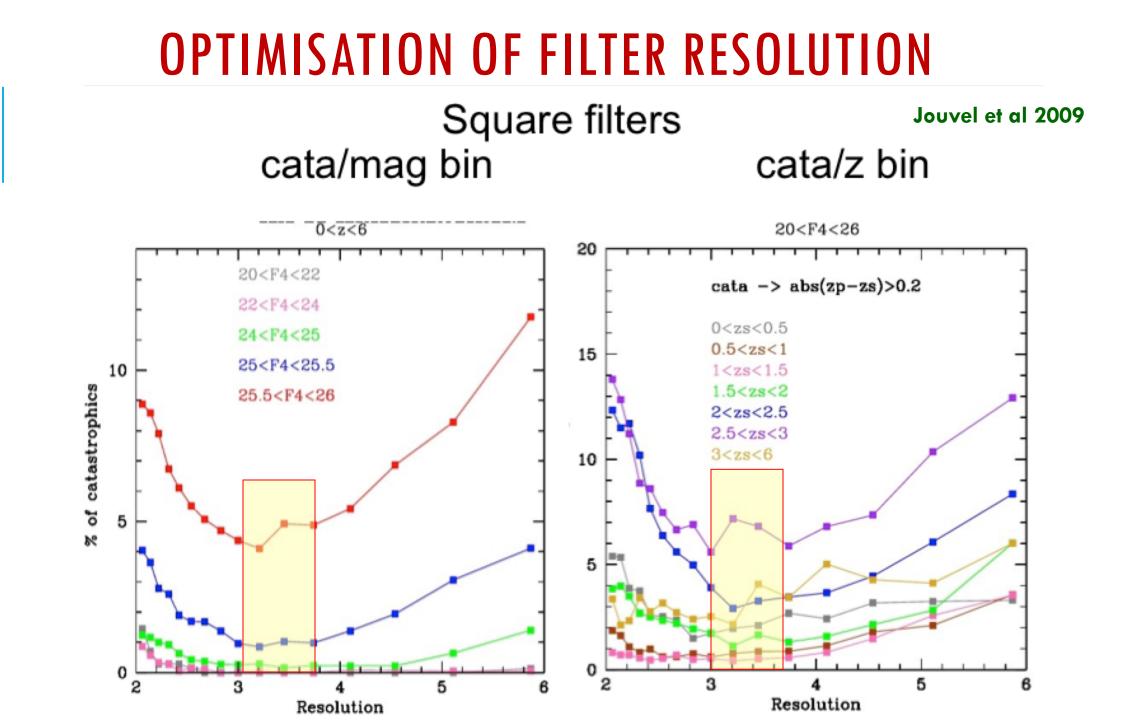
Improve depth by optimization of filter shape and resolution:

Square-ish filters preferred

Need to optimize resolution of filter

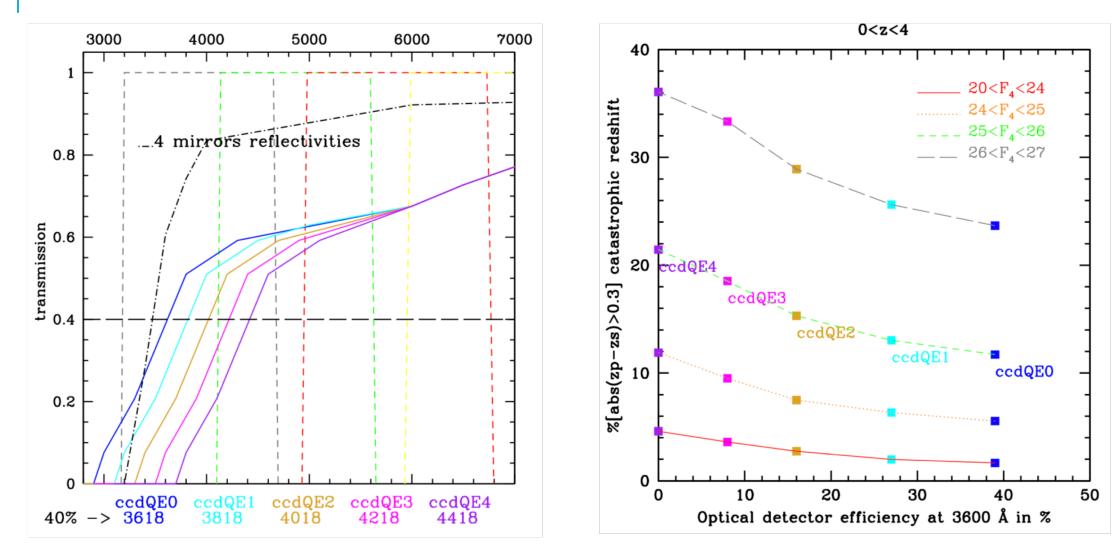
#### **OPTIMISATION OF FILTER RESOLUTION**





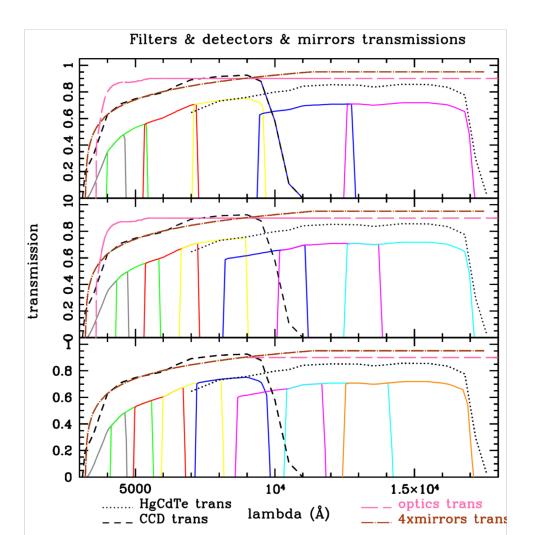
### **BLUE SENSITIVITY**

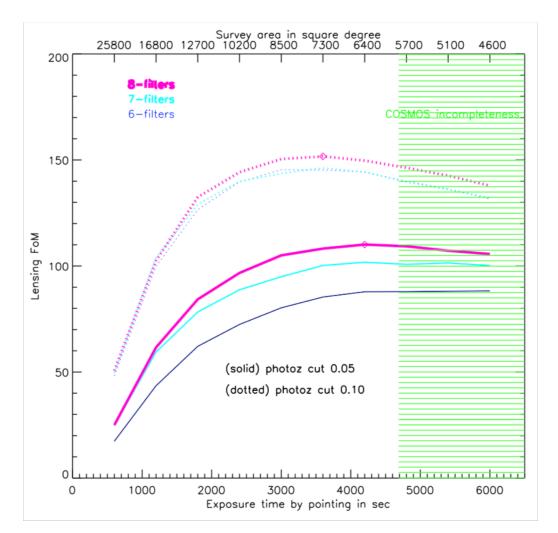
Jouvel et al 2011



#### NUMBER OF FILTERS

#### Jouvel et al 2011





### **PHOTO-Z SED CALIBRATION**

Need spectroscopic redshifts !!! Indeed galaxies SEDs likely evolves with type, redshift, age, luminosities, metallicity ...

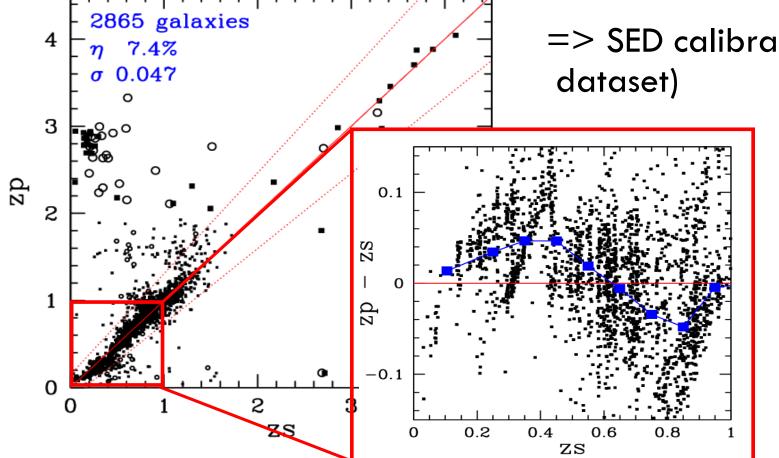
Redshift calibration should be done ideally on a representative population set: *i.e.* similar magnitude, redshift covering galaxy diversity => implication for the spectro survey

One may be able to optimize spectroscopic sample [i.e. one should spend less time on elliptical galaxies than starburst galaxies, one should spend sometime in calibrating e.g. the relatively rare objects such as type-2 AGNs].

### **CALIBRATION PROBLEM**

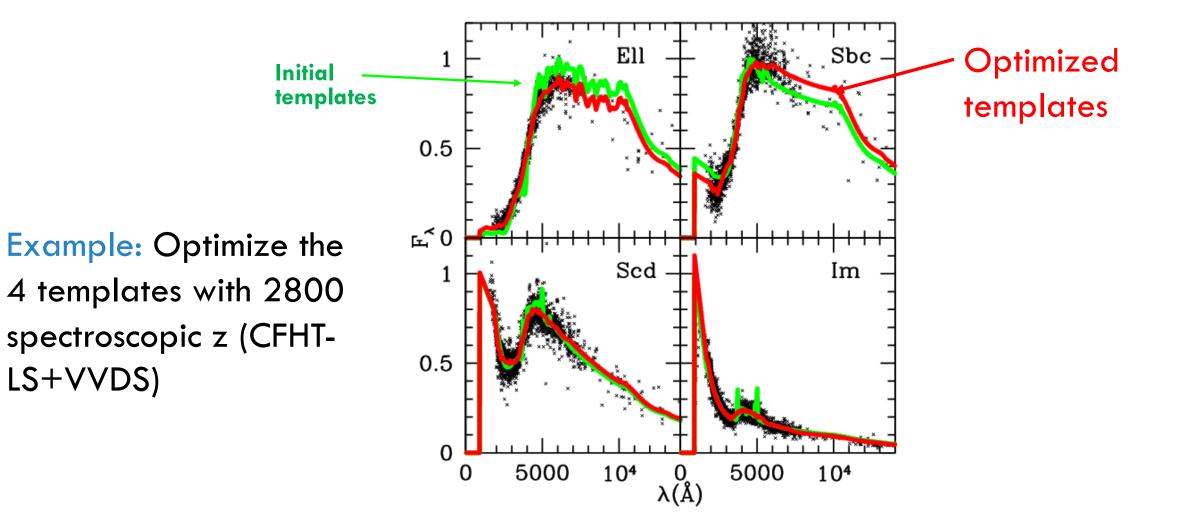
#### SED knowledge limited:

lead to important systematic => SED calibration (e.g. CFHT dataset)

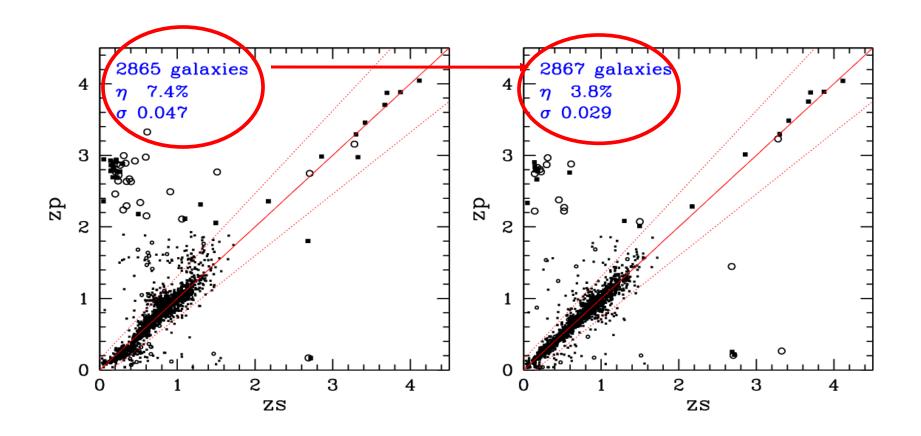


## **CALIBRATION - TEMPLATE OPTIMIZATION**

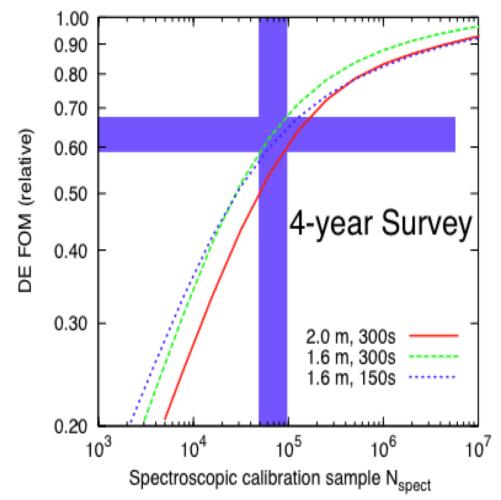
LS+VVDS)



### **CALIBRATION - IMPROVEMENT**



## SIZE OF SPECTROSCOPIC SAMPLE



Analysis by Zhaoming Ma

Shear tomography only

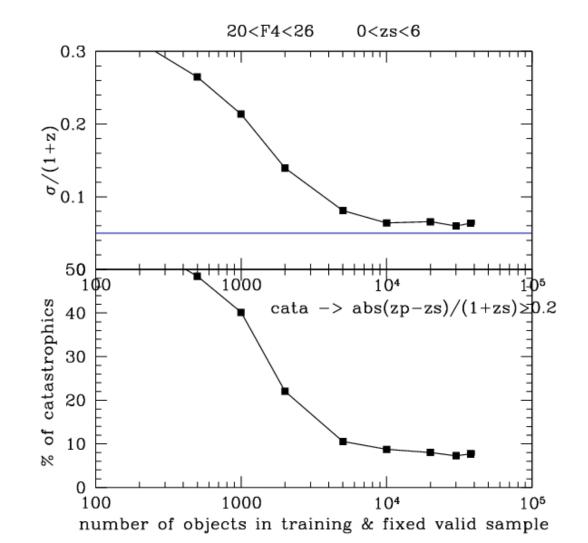
No other systematics

Z survey is only info about photo-z error distribution

Core distribution is double Gaussian with 4 free parameters per 0.1 redshift interval; fiducial distribution is the one generated by LePhare

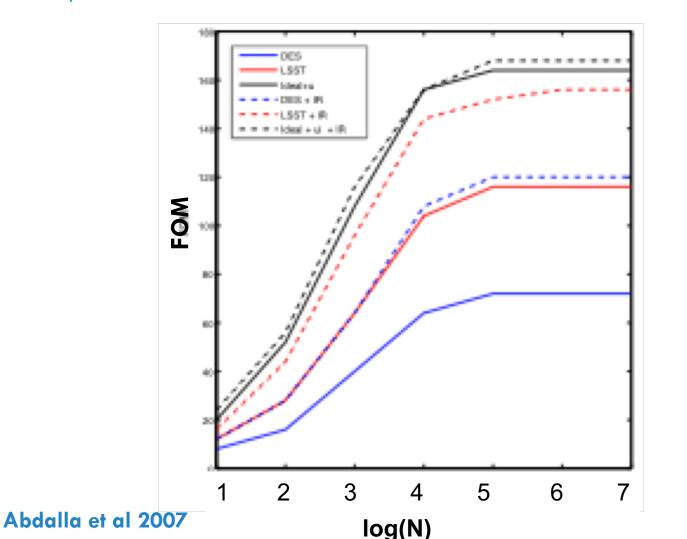
Deeper survey appears to need more redshifts.

### **NEURAL NET ESTIMATION OF SPECTRO-Z**



 COSMOS-SNAP simulation - with limited number of SEDs (8), requires a minimum 10<sup>4</sup> galaxies with redshift • BUT likely a lower limit, because of simple SED model

## **NEURAL NET ESTIMATION OF SPECTRO-Z**



Competitors analysis
Number of redshift for training set of neural-net photo-z ~ number of
spectro-z
DE FOM reach a plateau at 10<sup>5</sup> redshift

#### WHAT WE LEARNED FROM SNAP STUDIES

#### Photo-z accuracy/bias and number of catastrophic depend on:

- Number of filter, filter set, detectors efficiency (blue)
- Photometry calibration
- Spectro-z calibration
- Survey strategy

#### Tools for filter optimisation are ready and recommend:

- "U-band filter" => blue sensitivity below 400nm (>30%@400nm, >20%@350nm)
- Square-ish filter, log scaling, with resolution  $\sim$ 3.2 (for 6-8 filters)

#### Crucial need of spectro-z for photo-z calibratrion

- Low dispersion spectroscopy OK
- Need to cover the full population of galaxies probe (mag, z), importance of  $\lambda$  coverage of spectrograph
- N~10<sup>4</sup>-10<sup>5</sup> spectroscopic sample needed (NN number) possibly N~10<sup>6</sup>-10<sup>7</sup>
- importance of spectrograph field of view and survey strategy

### WHAT WE LEARNED IN THE LAST YEARS

#### >SNAP was not selected – died in 2008

#### Euclid too small to do photo-z from space – do only IR, rely on LSST for Photometric redshift

> But having 2 facilities with different timescale, objectives, survey strategy, collaboration, systematics ... will not make things simple ... and we will have to wait the end of both experiments to make the best of the two measurements

#### >Self-contained experiment better!

Lots of improvement in photo-z techniques (but intrinsic limitations are given by the observations/survey strategy)

#### Important to optimize the telescope/filter-set for best photo-z measurement

Spectroscopic survey important for calibration (BOSS/eBOSS, MUSE, DESI, PFS, MOONS, SDSS-V ... are all these enough? Or not?)